



**Device Type: Shade/Motor Control** 



GENERAL INFORMATION			
SIMPLWINDOWS NAME:	Somfy UAI+ v1.1 Endpoint Control		
CATEGORY:	Shades/Drapes		
VERSION:	1.1		
SUMMARY:	This module provides control functionality for an endpoint (single or group of motors) connected to a Somfy UAI+.		
GENERAL NOTES:	This is a standalone "component" module allowing for controlling a single motor or a group of motors, referred to in this document as an "endpoint".  This module requires an instance of the primary "Somfy UAI+ v1.1 Command Processor IP" communication module be included in the program. Control for this "component" module will be bound to and flow through the primary Comm module.		
CRESTRON HARDWARE REQUIRED:	Crestron 3-Series processor.		
SETUP OF CRESTRON HARDWARE:	This module requires the "Somfy UAI+ v1.1 Command Processor IP" module in order to operate. Please read the help file associated with that module for additional information.		
VENDOR FIRMWARE:	N/A		
VENDOR SETUP:	N/A		





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PARAMETER:	
Command_Processor_ID	Setting to indicate the instance of a particular UAI+ Comm module that this "component" module will be linked to. Up to 100 separate UAI+ Comm modules may be used in a single program, each one operating independently. This parameter is used to assign this particular component module to a specific UAI+.
Endpoint_Type	Setting to indicate the type of endpoint to be controlled, either a Single motor or a Group of motors.
Device_ID	Setting to indicate the Device ID of the endpoint. The meaning of this parameter will differ depending on the Endpoint_Type selected. If EndPoint_Type is Single, this will be the Device ID for the single motor you would like to control. If the Endpoint_Type is Group, this will be the Device ID for the single motor in your group to use for status feedback.
Group_ID	Setting to indicate the Group ID to control. This value is only relevant if Endpoint_Type selected is Group. If Endpoint_Type is Single, double quotes ("") should be used in this field.









CONTROL:		
Move_Up	D	Pulse to move the endpoint up.
Move_Down	D	Pulse to move the endpoint down.
Move_Stop	D	Pulse to stop the movement of the endpoint.
Move_To	D	Set the absolute position of the motor between 0 (fully up) and 100 (fully down).
Move_Relative_Up	Α	Move the motor up relative to its current position. The value entered corresponds to "pulses" on the motor so the motor will move up X number of pulses relative to where it currently is.
Move_Relative_Down	Α	Move the motor down relative to its current position. The value entered corresponds to "pulses" on the motor so the motor will move down X number of pulses relative to where it currently is.
Move_IP_Next	D	Pulse to move to the next pre-defined "intermediate" position. Note, intermediate positions can only be recalled from this module. Actual set up of intermediate positions to be performed using the UAI+ software or webpage.
Move_IP_Prev	D	Pulse to move to the previous pre-defined "intermediate" position. Note, intermediate positions can only be recalled from this module. Actual set up of intermediate positions to be performed using the UAI+ software or webpage.
Move_IP	Α	Pulse to recall a specific pre-defined "intermediate" position. Note, intermediate positions can only be recalled from this module. Actual set up of intermediate positions to be performed using the UAI+ software or webpage.



## **Certified Module**

Partner: Somfy Model: UAI+

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FEEDBACK:		
Motor_ls_Initialized	D	High to indicate that the module state is currently in sync with the state of the endpoint.
Motor_Current_Position	Α	Value indicating the current position of the motor between 0 (fully up) and 100 (fully down).





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**TESTING:** 

**OPS USED FOR TESTING:** CP3: 1.501.2867.24563

SIMPL WINDOWS USED FOR TESTING: 4.07.03

CRES DB USED FOR TESTING: 63.00.004.00

**DEVICE DATABASE:** 85.00.002.00

**SYMBOL LIBRARY USED FOR TESTING: 1033** 

SAMPLE PROGRAM: Somfy UAI+ v1.1 Demo IP CP3

v1.0 - Initial Release

**REVISION HISTORY:** v1.1 – fixed SIMPL# namespace/naming issue to allow for using UAI+ modules with myLink

modules in same program